

Branching program

- · Acyclic directed graph
- Two sinks: 1-sink and 0-sink
- All vertices labeled by variables
- · Value: sink label at the end of the path that corr. to the subst.
- Size = number of nodes

Nondeterministic branching program

- Has nodes without labels
- · Value equals one if there exists a path from source to 1-sink
- Size = number of labeled nodes

Read-once branching program

• Every path has only *1* occurrence of each variable

Minimum Circuit Size Problem

Input:

• truth table of a Boolean function $f: \{0, 1\}^n \rightarrow \{0, 1\}$ • size parameter *s*

Output: yes, if f can be computed by a circuit of size at most s

In a **Partial** MCSP input is a truth-table of a partial f

Hardness of MCSP for BPs implications

Theorem: if MCSP cannot be computed by a branching program of size $N^{2.01}$ then NP $\not\subset C$ -SIZE[n^k] for all k [Chen, Jin, Williams, 2019]

The best lower bound: BP(ED)= $\Omega\left(\frac{n^2}{\log^2 n}\right)$ [Nechiporuk, 1966] To develop new techniques to show lower bounds for BPs we study hardness of restricted versions of BP

(n x n)-Bipartite Permutation Independent Set Problem



- Graph with 2n x 2n vertices,
- Edges exist only between vertices from two quadrants
- Need to find exactly one vertex from every row, and exactly one vertex from every column, such that
- These vertices are from the two quadrants
- These vertices form independent set

MCSP is Hard for Read-Once Nondeterministic Branching Programs

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Theorem: size of 1-NBP computing MCSP is $N^{\Omega(\log \log N)}$

This result is tight for MCSP with linear size parameter.

To prove this lower bound we adapt a framework from the work [Ilango 2020], in which the author showed an ETH-hardness of partial MCSP.





(a)

EPFL

Main result

Sketch of the proof of the Theorem: Assume there is a small 1-NBP computing MCSP. As the sizes of 1-NBP for MCSP and Partial MCSP are polynomially related, there is a small 1-NBP computing Partial MCSP.

Then, from this small 1-NBP for Partial MCSP we can get a small read-once 1-NBP for (n x n)-BPIS. Which is impossible unconditionally. Hence, MCSP cannot be computed by a small 1-NBP.

Show tight lower bound for MCSP with higher size parameters • The same technique cannot work, as we cannot construct a truth table of a function with higher than linear circuit complexity

Extend this result to other models of computations • For any model in which (n x n)-BPIS is hard and the reduction to the truth table is efficiently computable the same size lower bound

	MCS	P
Have the same 1-NBP complexity		
size of the minimal 1-NBP computing equals the size of the minimal 1–NBP CSP		
1 O Partial		
	1-NBP for MCSP	
MCSP	1-NBP for Partial	
	MCSP	

Future work