

The Complexity of Verifying Boolean Programs as Differentially Private

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Joint work with Mark Bun and Marco Gaboardi

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Plan of the talk

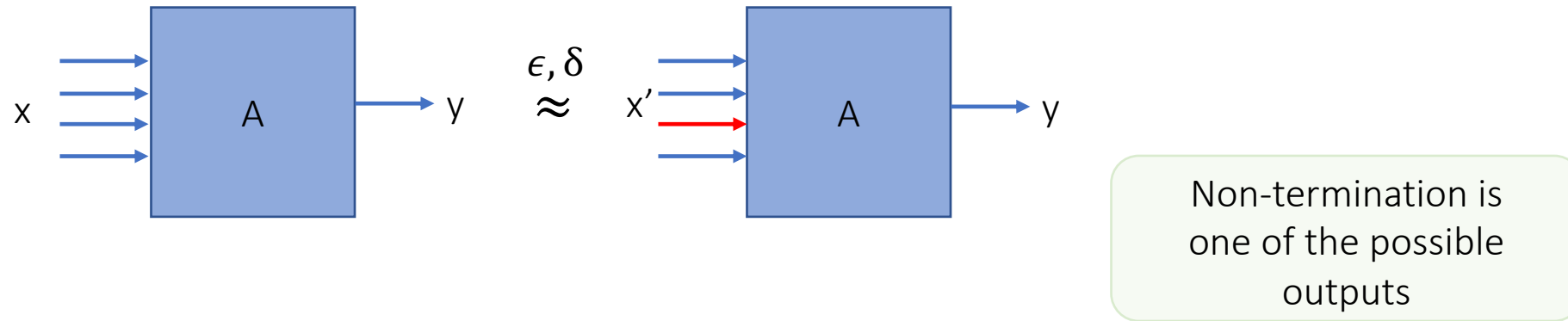
1. Prior work

- How hard is it to verify whether a program is DP for
 - Turing-complete languages
 - Boolean languages with bounded memory without loops

2. Our results and proof ideas

- BPWhile: Boolean language with loops and finite memory
- PSPACE-completeness of the verification of the DP for BPWhile
- PSPACE-hardness: reduction from TQBF
- PSPACE algorithm based on computing hitting probabilities in a Markov chain

Differential Privacy



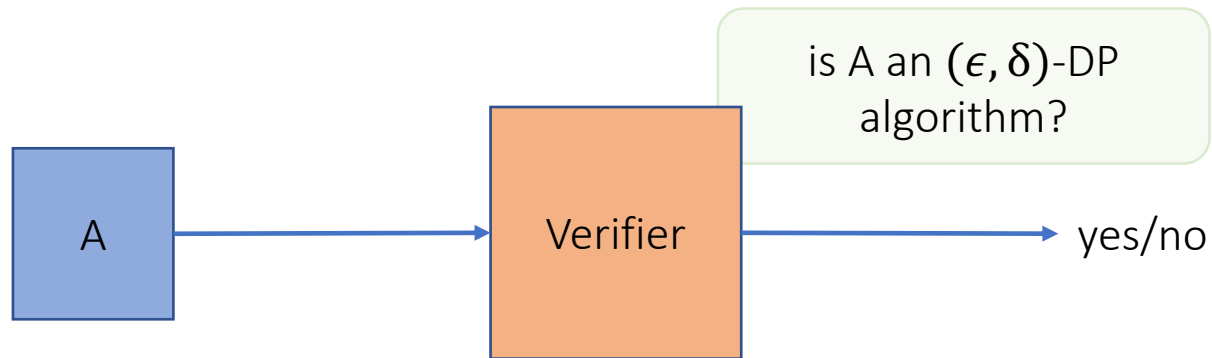
C is (ϵ, δ) -differentially private if for every set of possible outputs O , and for every neighboring x, x' :

$$P[C(x) \in O] \leq e^\epsilon \cdot P[C(x') \in O] + \delta$$

Neighboring relation we consider:

- Inputs differ in one bit
- Can be extended to any bounded polyspace computable relation

Verification of Differential Privacy



Complexity of verification depends on the expressivity of the language:

- For languages working with infinite data
 - Undecidable
 - \Rightarrow Undecidable for Turing-complete languages
- For a simple Boolean language with **bounded memory**, if statements and **random assignments**, but **without loops**
 - $coNP^{\#P}$ -completeness for $(\epsilon, 0)$ -DP
 - Reduction from All-Min-SAT
 - $coNP^{\#P}$ and in $coNP^{\#P^{\#P}}$ for (ϵ, δ) -DP

[Barthe, Chadha, Jagannath, Sistla, Viswanathan'20]

[Gaboardi, Nissim, Purser'20]

Verification of DP: Black box vs White box

Complexity also depends on the type of access to the code:

- No information about the algorithm, query access
 - Impossible to verify $(\epsilon, 0)$ -DP
- Full access to the code/representation:
 - Linear algorithm in the size of automaton
 - For pure-DP
 - #P-hardness for approximating parameters in labelled Markov chains
 - For approximate-DP
 - Undecidable to compute exactly

[Gilbert, McMillan'19]

[Chadha, Sistla, Viswanathan'21]

[Chistikov, Murawski, Purser'19]

In this work: **white-box** model

BPWhile: Boolean language with While loops

We design the language for the following goals:

- Captures classical computations on real computers
- Simple to analyze

$x ::= [a - z]^+$ Variable identifiers

$b ::= true \mid false \mid random \mid x \mid b \wedge b \mid b \vee b \mid !b$ Boolean expressions

$c ::= skip \mid x := b \mid c; c \mid \text{if } b \text{ then } c \text{ else } c \mid \text{while } b \text{ then } c$ Commands

$t ::= x \mid t, x$ List of Boolean variables

$p ::= input(t); c; return(t)$ Programs

Numbers of variables and input bits are fixed in the definition of the program

⇒ Length of the program is an upper bound on the size of the memory that the program uses

Example of a BPWhile program:

```
0.  input( $\vec{c}, n, \epsilon$ );
1.   $\vec{k} := \lceil \log(2/\epsilon) \rceil$ ;
2.   $\vec{d} := (2^{\vec{k}+1} + 1)(2^{\vec{k}} + 1)^{n-1}$ ;
3.   $\vec{u} := \text{uniform}(0, \vec{d}]$ ;
4.   $\vec{z} := 0$ ;
5.   $\vec{r} := n$ ;
6.  while  $\vec{z} < \vec{n} \wedge \vec{r} = n$  then
7.    if  $\vec{z} < \vec{c}$  then
8.      if  $\vec{u} \leq 2^{\vec{k}(\vec{c}-\vec{z})}(2^{\vec{k}} + 1)^{n-(\vec{c}-\vec{z})}$ 
9.        then  $\vec{r} := \vec{z}$ 
10.     else skip
11.   else
12.     if  $\vec{u} \leq d - 2^{\vec{k}(\vec{z}-\vec{c}+1)}(2^{\vec{k}} + 1)^{n-1-(\vec{z}-\vec{c})}$ 
13.       then  $\vec{r} := \vec{z}$ 
14.     else skip
15.    $\vec{z} = \vec{z} + 1$ ;
16. return( $\vec{z}$ );
```

Implementation of the Bounded Geometric Mechanism in finite precision arithmetic

[Ghosh, Roughgarden, Sundararajan'09]

[Balcer, Vadhan'17]

Our results

Main result: if A is a BPWhile program, then the problem of verifying whether A is differentially private is PSPACE-complete.

It holds for the following notions of differential privacy:

- $(\epsilon, 0)$ -DP
- (ϵ, δ) -DP
- (ϵ, δ) -DP parameters approximation
- Renyi-DP
- Zero-Concentrated-DP
- Truncated Concentrated-DP

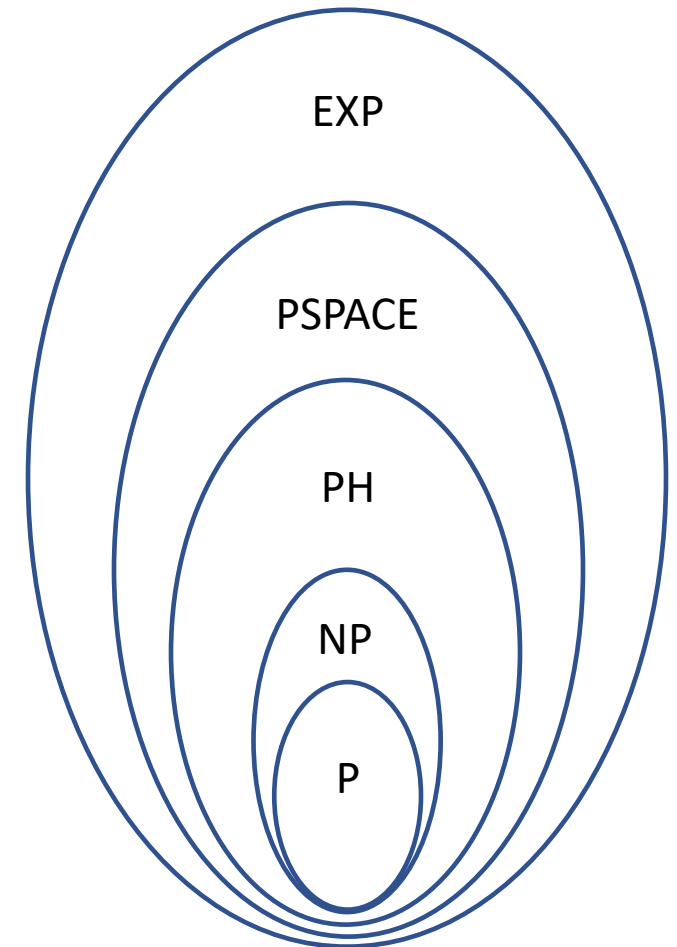
PSPACE-completeness

PSPACE-completeness of a problem A implies:

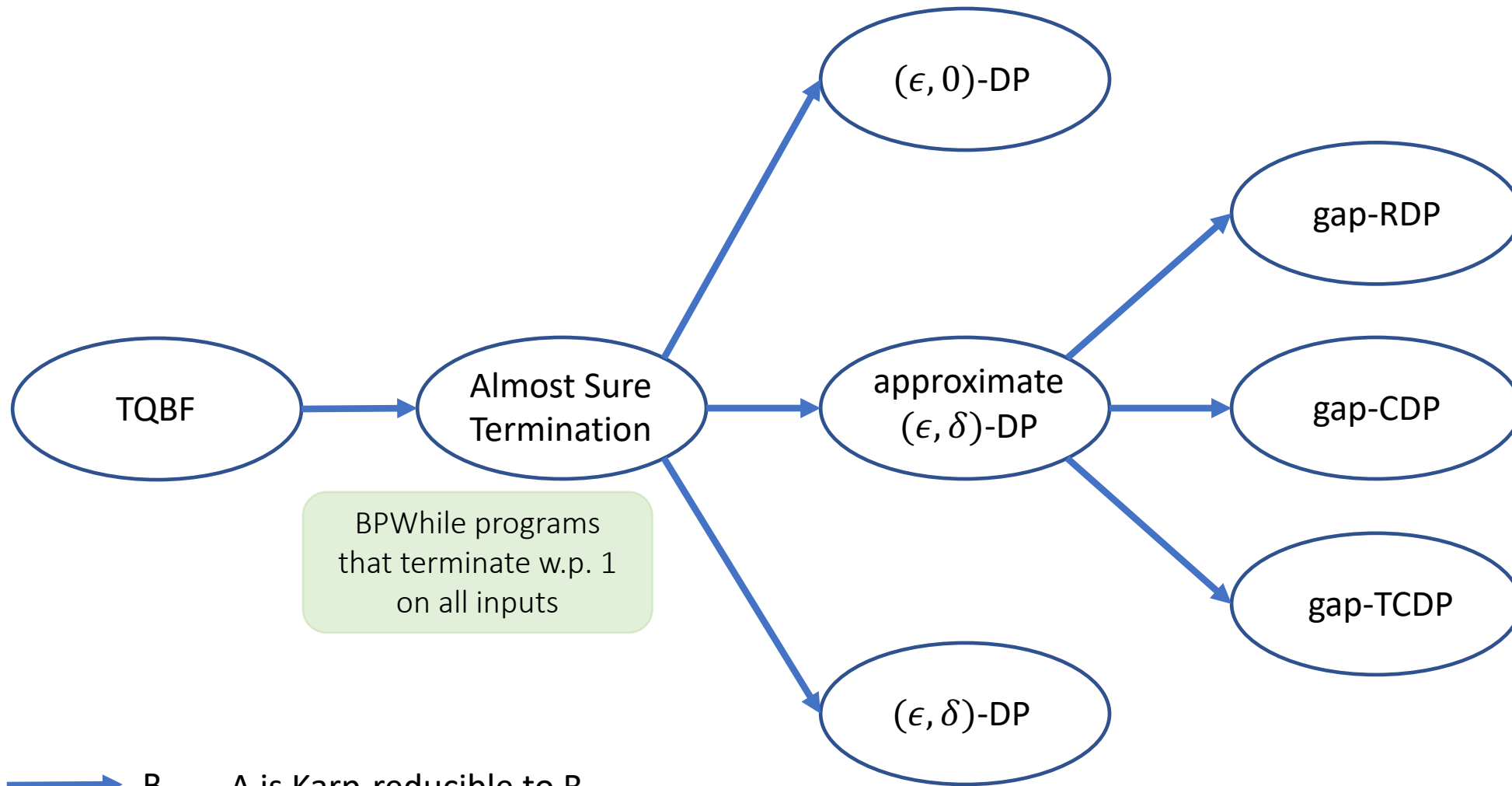
- A is solvable by a TM that uses polynomial space
- A is solvable in exponential time
- A is at least as hard as any problem solvable in polyspace
- No polytime algorithm for A , unless $P = PSPACE$
 - That is widely believed not to be true

To show PSPACE completeness we need:

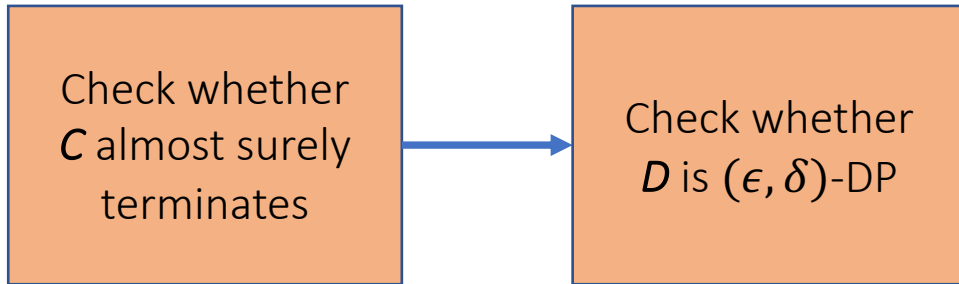
1. Show hardness: construct sequence of reductions from TQBF
2. Construct polynomial-space algorithm: analyze Markov chain based on the state graph of the program



PSPACE-hardness



PSPACE-hardness: illustrative reduction



We need to show that

C almost surely terminates $\Leftrightarrow D$ is (ϵ, δ) -DP

C almost surely terminates $\Rightarrow D$ is (ϵ, δ) -DP

If C terminates w.p. 1, then for all x :

- $D(x, 1)$ doesn't terminate w.p. δ
- $D(x, 1)$ terminates and outputs 1 w.p. $1 - \delta$
- $D(x, 0)$ doesn't terminate w.p. 0
- $D(x, 0)$ terminates and outputs 1 w.p. 1

D:

```
1. input (x, b);
2. if b == 1 then
3.     C(x);
4.     r = delta_rand();
5.     if r == 0 then
6.         while true then
7.             skip;
8.         else skip;
9.     else skip;
10. return (1)
```

Copy of a program that returns 0 w.p. delta

PSPACE-hardness: illustrative reduction

Checked:

C almost surely terminates $\Rightarrow D$ is (ϵ, δ) -DP

Need to check:

C doesn't almost surely terminate $\Rightarrow D$ is not (ϵ, δ) -DP

If C doesn't terminate w.p. p on x :

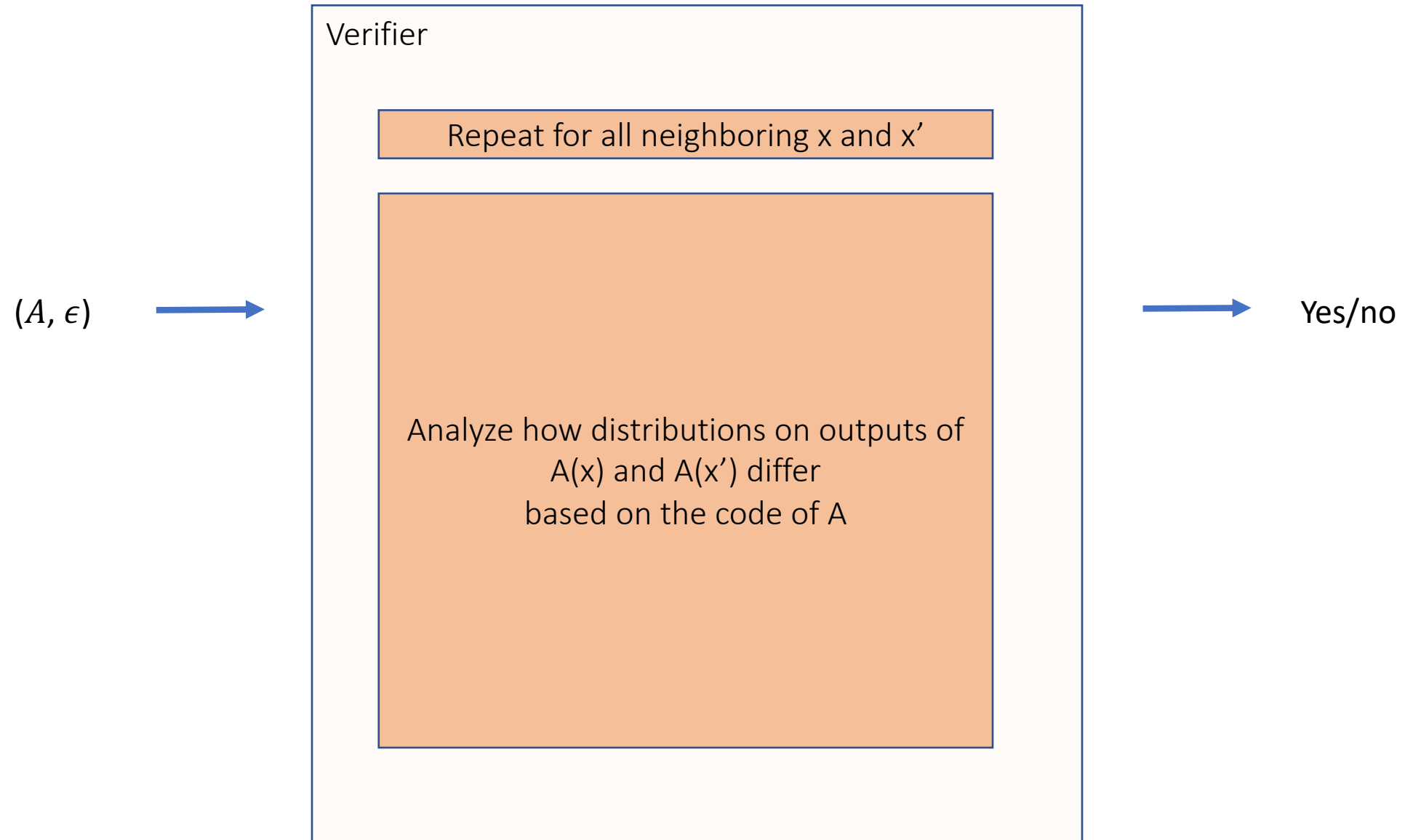
- $D(x, 1)$ doesn't terminate w.p. $p + (1 - p)\delta > \delta$
- $D(x, 1)$ terminates and outputs 1 w.p. $< 1 - \delta$
- $D(x, 0)$ doesn't terminate w.p. 0
- $D(x, 0)$ terminates and outputs 1 w.p. 1

D:

```
1. input (x, b);
2. if b == 1 then
3.     C(x);
4.     r = delta_rand();
5.     if r == 0 then
6.         while true then
7.             skip;
8.         else skip;
9. else skip;
10. return(1)
```

Copy of a program that returns 0 w.p. delta

Polyspace membership: algorithm for $(\epsilon, 0)$ -DP

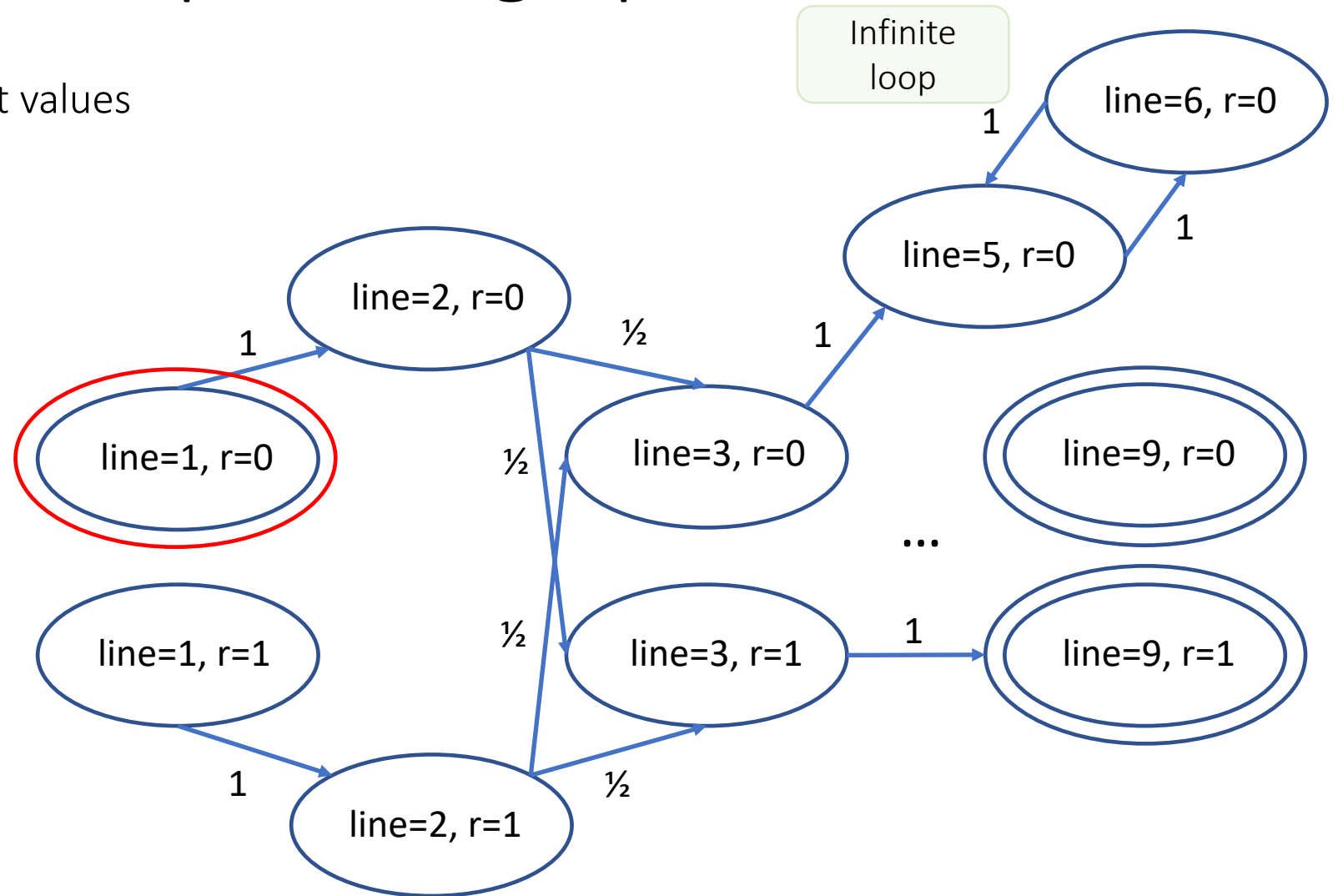


PSPACE membership: state graph

State graph depends on the input values

D(b=1):

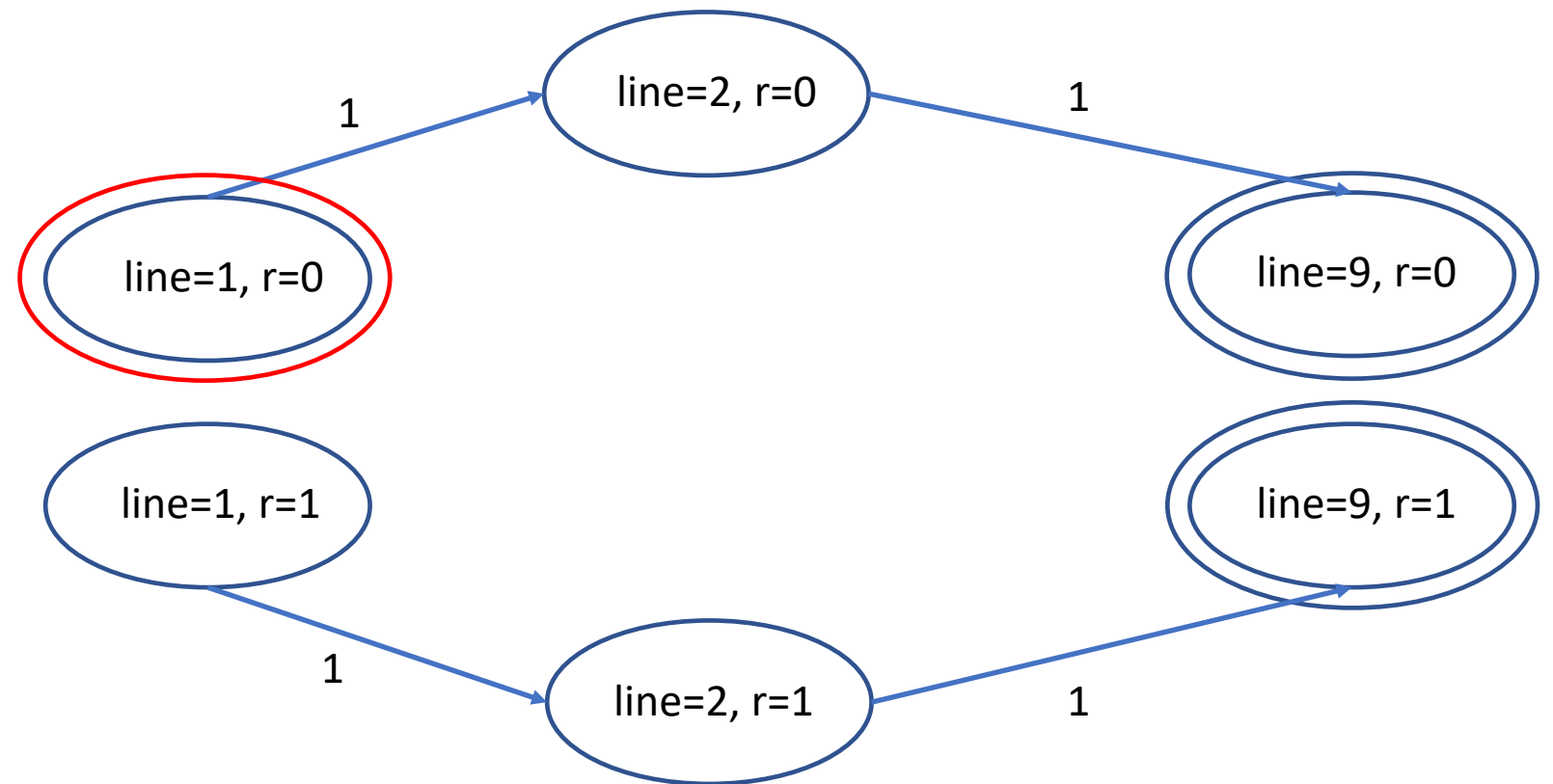
```
1. input(b);
2. if b == 1 then
3.     r = rand();
4.     if r == 0 then
5.         while true
6.             skip;
7.     else skip;
8. else skip;
9. return(1)
```



PSPACE membership: state graph

D(b=0):

```
1. input(b);  
2. if b == 1 then  
3.     r = rand();  
4.     if r == 0 then  
5.         while true  
6.             skip;  
7.     else skip;  
8. else skip;  
9. return(1)
```



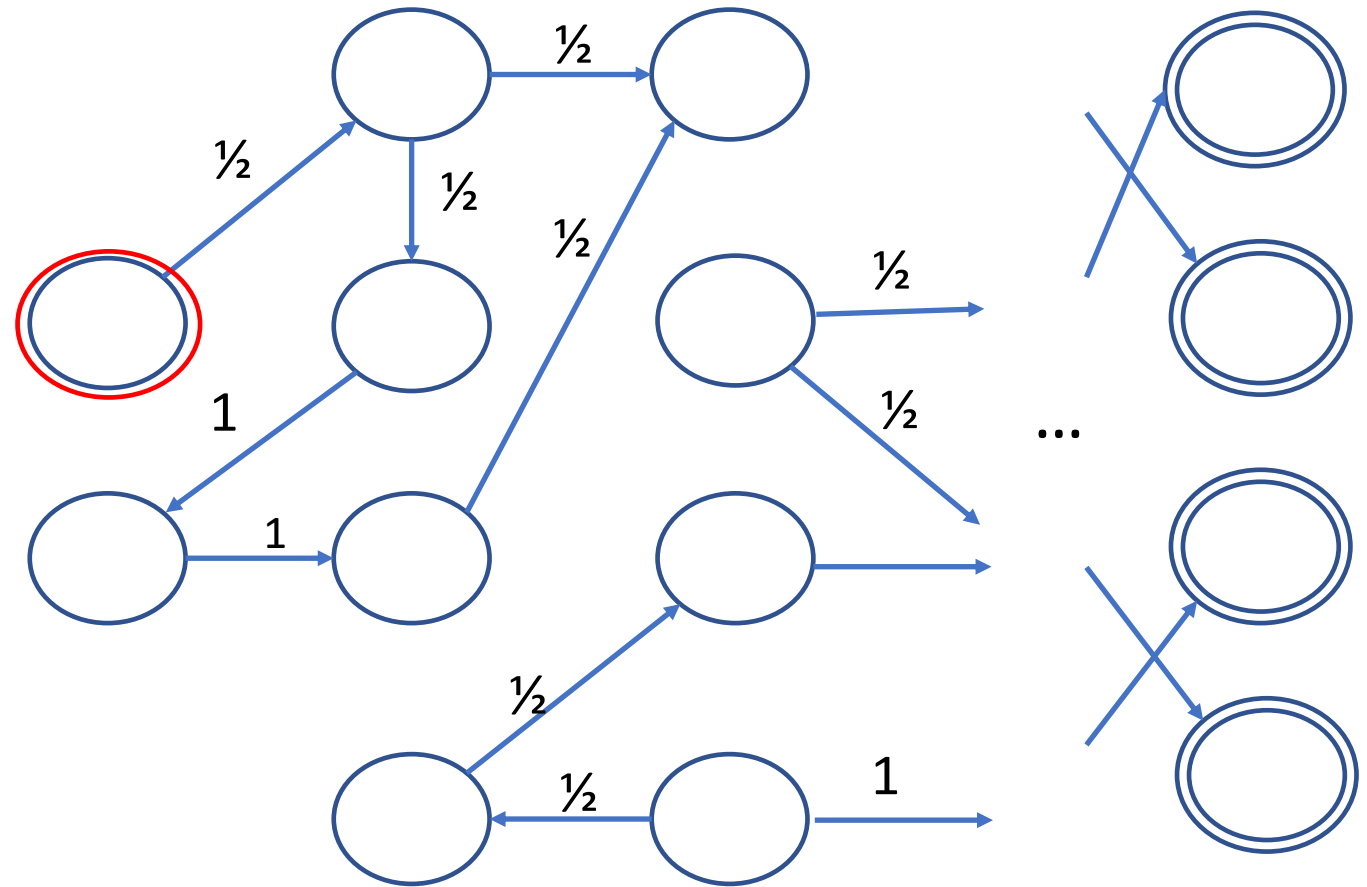
PSPACE membership: algorithm for $(\epsilon, 0)$ -DP

For a program D and all neighboring inputs x, x' :

- Construct the Markov chain for $D(x)$ and $D(x')$
- Compute and compare hitting probabilities

Problem: Markov chain has exp-many states \Rightarrow cannot store it explicitly

Need **space-efficient** algorithm for computing hitting probabilities with **implicit access** to the Markov chain



Polyspace algorithm for computing hitting probabilities in a Markov chain

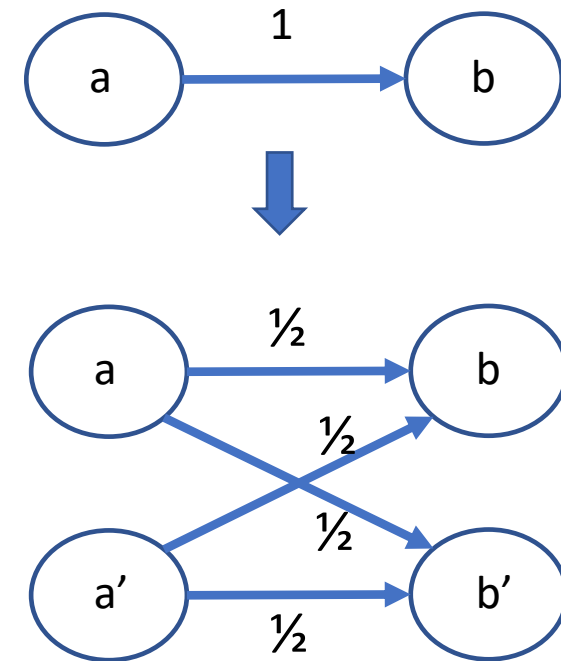
Lemma [Simon'81]: M is a Markov chain with at most 2^L states

- initial distribution placing all mass on one state,
- a set of final states F each with only one self-transition,
- every non-final state has outgoing transition probability 0 or $\frac{1}{2}$.

Then, there is an $O(L^6)$ -space deterministic algorithm that computes the hitting probabilities of every state in F .

Note: to use the algorithm, we need to replace all transitions labelled by 1 in the state graph of the BPWhile program:

- Clone all states
- For each state a with outgoing edge w.p. 1 replace it by two edges:
 - Edge (a,b) with weight $\frac{1}{2}$ to original state
 - Edge (a,b') with weight $\frac{1}{2}$ to the clone-state b' of b



PSPACE membership: exponentially long numbers

For a program D

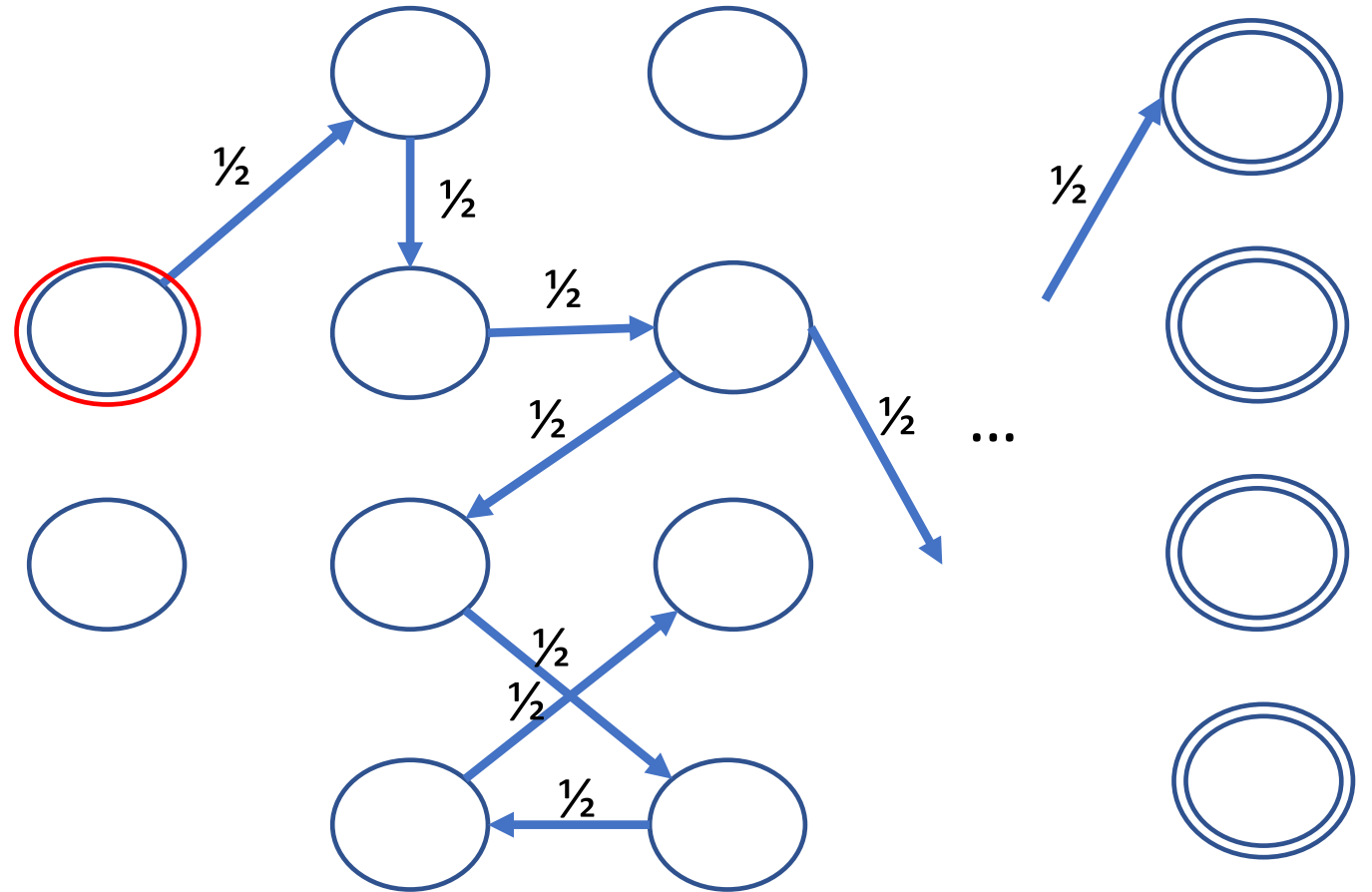
for all neighboring inputs x, x' :

- Construct the Markov chain for $D(x)$ and $D(x')$
- Compare hitting probabilities of the final states with the same values

Problem:

Markov chain has exp -many states
 \Rightarrow hitting probabilities can be as small as $\frac{1}{2^{exp}}$

\Rightarrow numbers are exponentially long



Operations with exponentially long numbers

$$\begin{array}{r} 1\ 0\ 1\ 1\ 1\ \dots\ 1\ 0\ 0\ 1 \\ +\ 0\ 0\ 1\ 0\ 1\ \dots\ 1\ 1\ 1\ 1 \\ \hline 1\ 1\ 1\ 0\ 1\ \dots\ 1\ 0\ 0\ 0 \end{array}$$

Uniform family of log-depth circuits:

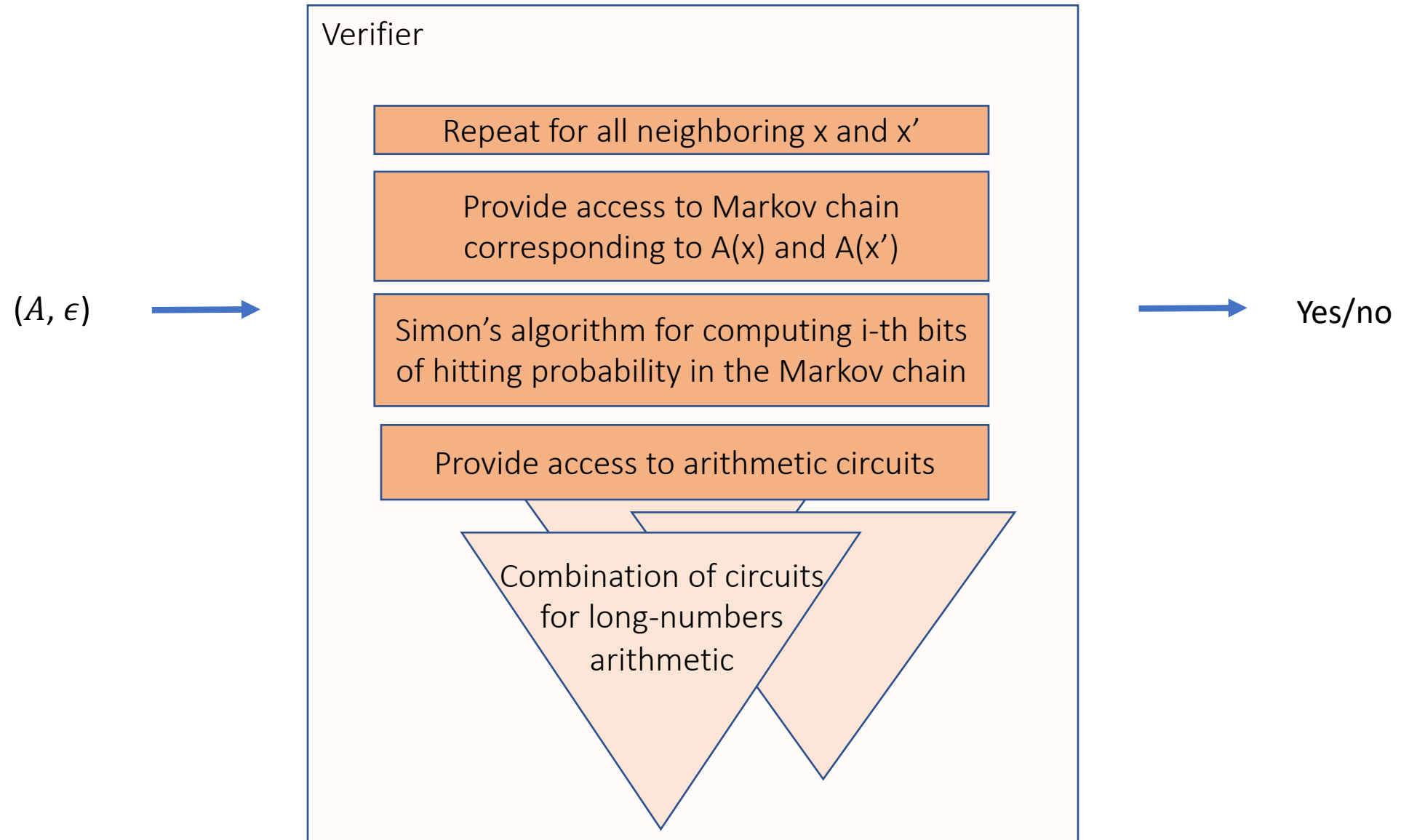
- One logspace algorithm provides implicit access to the circuits
- Each circuit has log-depth and poly size

Lemma:

Uniform families of log-depth circuits exist for:

- Comparison
- Addition
- Multiplication by a fixed rational number
- Multiplication [Ofman'62]
- Square roots [Reif'86]

Polyspace membership algorithm for $(\epsilon, 0)$ -DP



Polyspace algorithm for RDP, zCDP, TCDP

An algorithm is **RDP/zCDP/TCDP** if for a privacy parameter ρ and a fixed/any/bounded $\alpha > 1$ Rényi divergence for any neighboring inputs x, x' is at most $\rho\alpha$

[Mironov'17],[Dwork-Rothblum'16,Bun-Steinke'16],
[Bun,Dwork,Rothblum,Steinke'18]

New problems:

- To compute Rényi divergence we compute
 - Logarithms
 - Exponentiations to rational degrees
- Hence, get infinite fractions

Solution:

- Computations with a fixed precision η
- Consider gap-versions of the problem

$$D_\alpha(P|Q) = \frac{1}{\alpha - 1} \log \sum \frac{p_i^\alpha}{q_i^{\alpha-1}}$$

We define Gap-RDP on $(\mathcal{C}, \rho, \alpha, \eta)$ as follows:

- Yes-instance, if for all neighboring x, x'

$$D_\alpha(\mathcal{C}(x)|\mathcal{C}(x')) \leq \rho\alpha$$

- No-instance, if for at least one neighboring x, x'

$$D_\alpha(\mathcal{C}(x)|\mathcal{C}(x')) \geq \rho\alpha + \frac{1}{2\eta}$$

Polyspace algorithm for zCDP

Another problem: an algorithm is zCDP if for all values of α Rényi divergence for any neighboring inputs x, x' is bounded by $\rho\alpha$

Solution: showed that it is sufficient to check values of alpha from **the bounded range:**

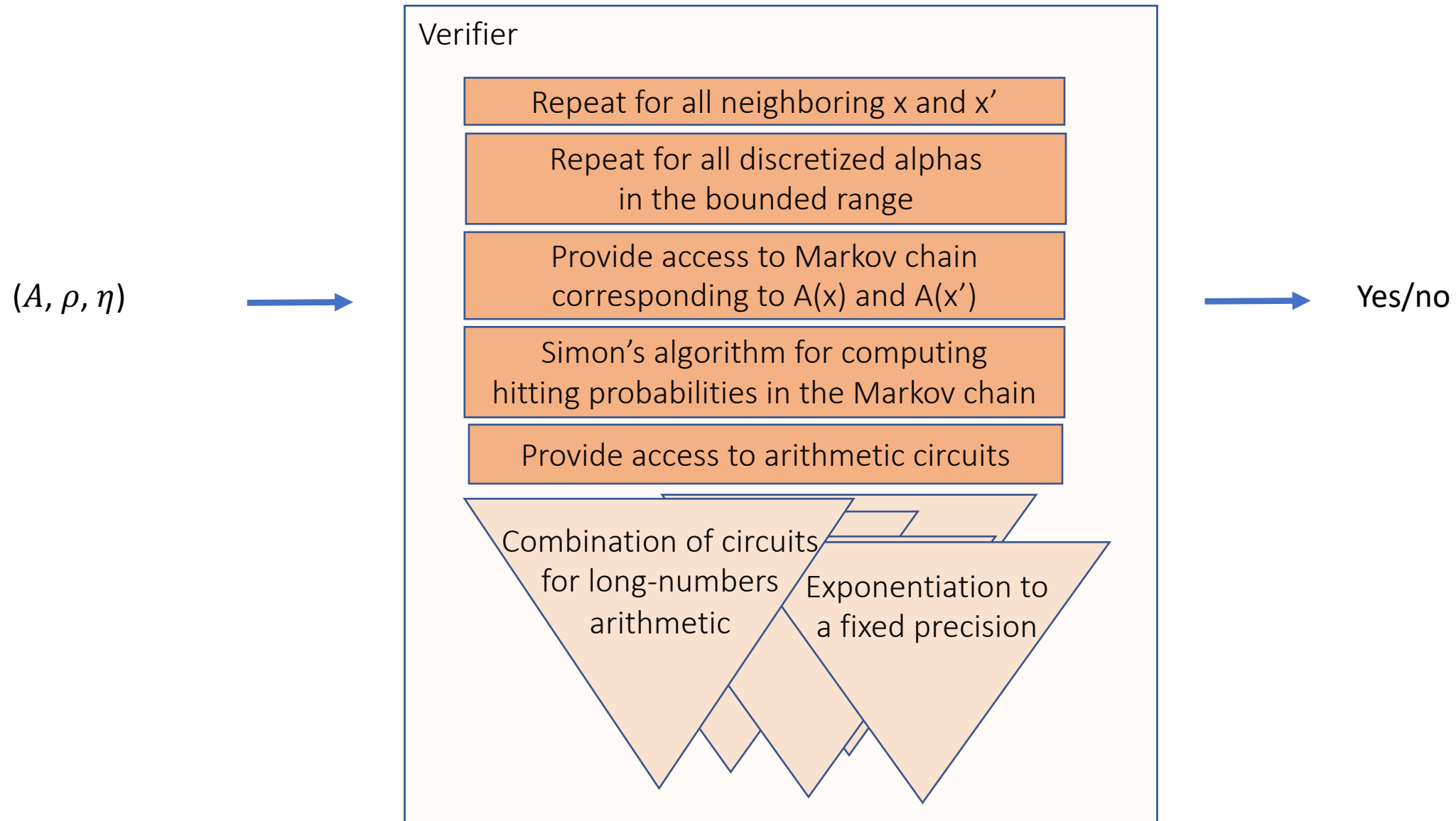
Lemma:

C is ρ -zCDP, then for all neighboring x, x' : $D_\alpha(C(x) | C(x')) \leq \rho\alpha$

C is not $(\rho + 2^{-\eta})$ -zCDP \Rightarrow exists neighboring x, x' , exists $\alpha \in (1, 1 + 2^{\text{poly}(n)} / \rho)$:

- α is a multiple of $2^{-\eta}$
- $D_\alpha(C(x) | C(x')) \geq \rho\alpha + 2^{-\eta-1}$

Polyspace membership algorithm for Gap-zCDP



Results and future work

- We showed PSPACE-completeness for the problems of checking:
 - Pure-DP
 - Approximate-DP
 - Gap-RDP
 - Gap-zCDP
 - Gap-TCDP
- Possibly can extend the result to show PSPACE-completeness of verifying accuracy
- Improve the exact polynomial in the space complexity of the algorithm
 - Improved analysis and more efficient algorithms for Markov chains analysis and long-numbers arithmetic operations are needed for tighter results

